

About Us

While contributing to the sector by production of robots and robotic accessories towards plastics industry, **Moritech Robot** also carries on distributorship of international robot brands successfully.

Moritech Robot, by considering its customers as business partners, offers production solutions on the project basis in order to advance their production potential in the most effective manner possible with the help of high technology.





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MW 800II













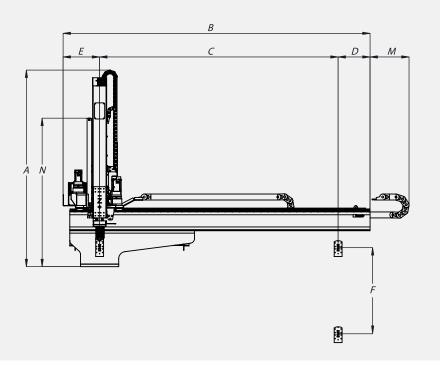


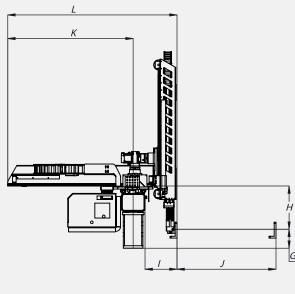


FUNDAMENTAL MECHANICAL SPECIFICATIONS

	Axis Strokes (mm)		nm)	Injection Clamping	Driving	Lineer Position	C Axis Postu	re 🗸 90°	Net Weight (kg)
Model	Vertical	Crosswise	Traverse	Force Range (Ton)	Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body
MW800II	800	440	1500	90 - 200	AC Servo Motor	±0.1	5 (*1)	25	305

^(*1) Weight of Robotic Hand is Included.





Α	Height	1484
В	Length	2056
С	Traverse Axis Stroke	1500
D	Traverse Axis Stroke Excluded Distance (Product Place Region)	250
Ε	Traverse Axis Stroke Excluded Distance (Product Pick Up Region)	306
F	Vertical Axis Stroke	800
M	Traverse Axis Cable Carrier Overflow	300
N	Balance Cylinder Height	1045

G	Vertical Wait	159
Н	Gripper Assembly Position under Crosswise Axis	363
I	Minimum Crosswise Wait	268
J	Maximum Crosswise Stroke	440
l+J	Maximum Crosswise Reach	708
L	Width	1024
K	Crosswise Start Distance	657

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	1.9	4 - 6	3.5

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- · Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking
- Product Sorting in Matrix Form
- Soft Sorting / Separation

- Y Axis Free
- Eco Mode (Automatic Energy Saving Cycle Feature)
- Product Extraction from Core in the Mold
- Sprue Separation
- Sample Separation
- Crosswise J (Pass) Motion
 - Defective Product Separation (Machine Feature Compatibility Support)
 - Message Support on the Control Panel
- IMM Door Open Permission during Pause

- Pause during Operation
- C Axis Rotation Control
- 90° Soft Stop
- Connection Adapter between Robot and Injection Machine
 Mode Operation Function Control
- Extra Mold Safety Sensor (Optional)
- Overload Protection
- Conveyor Control

- Multi Language Support
- Operation Record Feature
- Alarm Record Feature
- USB Memory Connection
- Memory of upto 999 Molds
- Ejector Control
- Euromap 12/67 Robot Interface
- Economic Vacuum Feature (Optional)

MW 1000II













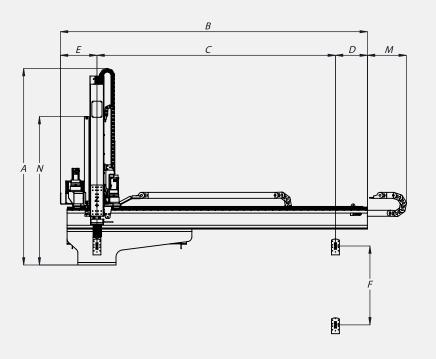


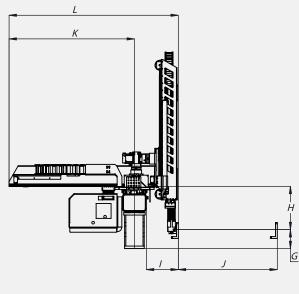


FUNDAMENTAL MECHANICAL SPECIFICATIONS

	Axis Strokes (mm)		Injection Driving		Lineer Position	C Axis Postu	Net Weight (kg)		
Model	Vertical	Crosswise	Traverse	Force Range (Ton)	Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body
MW1000II	1000 [1200]	660	1500 [1800] [2000]	150 - 300	AC Servo Motor	±0.1	5 (*1)	25	322 [325] - [345] [349]

(*1) Weight of Robotic Hand is Included.





Α	Height	1560 -	[1684]
В	Length	2056	[2356] [2556]
C	Traverse Axis Stroke	1500	[1800] [2000]
D	Traverse Axis Stroke Excluded Di (Product Place Region)	stance	250
Ε	Traverse Axis Stroke Excluded Di (Product Pick Up Region)	stance	306
F	Vertical Axis Stroke	1000 -	[1200]
M	Traverse Axis Cable Carrier Overflo	N	300
N	Balance Cylinder Height	1145 -	[1245]

G	Vertical Wait	159
Н	Gripper Assembly Position under Crosswise Axis	363
I	Minimum Crosswise Wait	268
J	Maximum Crosswise Stroke	660
I+J	Maximum Crosswise Reach	928
L	Width	1246
K	Crosswise Start Distance	884

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	1.9	4 - 6	3.5

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

([]) Optional Dimensions.

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking
- Product Sorting in Matrix Form
- Soft Sorting / Separation

- Y Axis Free
- Eco Mode (Automatic Energy Saving Cycle Feature)
- Product Extraction from Core in the Mold
- Sprue Separation
- Sample Separation
- Crosswise J (Pass) Motion
- Defective Product Separation (Machine Feature Compatibility Support)
- Message Support on the Control Panel
- IMM Door Open Permission during Pause

- Pause during Operation
- C Axis Rotation Control
- 90° Soft Stop
- Connection Adapter between Robot and Injection Machine
- Mode Operation Function Control
- Extra Mold Safety Sensor (Optional)
- Overload Protection
- Conveyor Control

- Multi Language Support
- Operation Record Feature
- Alarm Record Feature
- USB Memory Connection
- Memory of upto 999 Molds
- Ejector Control
- Euromap 12/67 Robot Interface
- Economic Vacuum Feature (Optional)

MW 120011













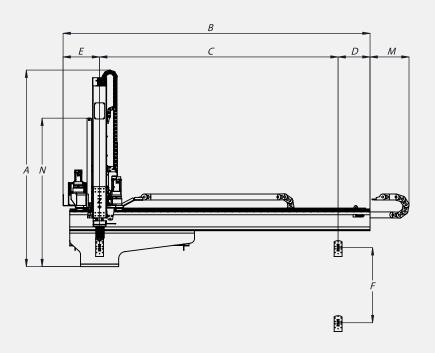


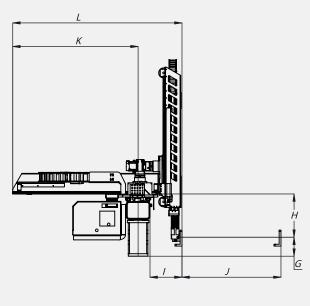


► FUNDAMENTAL MECHANICAL SPECIFICATIONS

	Axis Strokes (mm)		Injection Driving	Lineer Position	C Axis Postu	Net Weight (kg)			
Model	Vertical	Crosswise	Traverse	Force Range (Ton)	Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body
MW1200II	1200 [1400]	830	2000 [2500]	250 - 400	AC Servo Motor	±0.1	10	25	386 [392] - [433] [436]

(*1) Weight of Robotic Hand is Included.





Α	Height	1684 - [1810]
В	Length	2576 - [3056]
С	Traverse Axis Stroke	2000 - [2500]
D	Traverse Axis Stroke Excluded (Product Place Region)	Distance 270
Ε	Traverse Axis Stroke Excludec (Product Pick Up Region)	Distance 306
F	Vertical Axis Stroke	1200 - [1400]
M	Traverse Axis Cable Carrier Over	flow 300
N	Balance Cylinder Height	1245 - [1345]

G	Vertical Wait	159
Н	Gripper Assembly Position under Crosswise Axis	363
ı	Minimum Crosswise Wait	268
J	Maximum Crosswise Stroke	830
l+J	Maximum Crosswise Reach	1098
L	Width	1420
K	Crosswise Start Distance	1051

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	1.9	4 - 6	4.4

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

([]) Optional Dimensions.

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking
- Product Sorting in Matrix Form
- Soft Sorting / Separation

- Y Axis Free
- Eco Mode (Automatic Energy Saving Cycle Feature)
- Product Extraction from Core in the Mold
- Sprue Separation
- Sample Separation
- Crosswise J (Pass) Motion
- Defective Product Separation (Machine Feature Compatibility Support)
- Message Support on the Control Panel
- IMM Door Open Permission during Pause

- Pause during Operation
- C Axis Rotation Control
- 90° Soft Stop
- Connection Adapter between Robot and Injection Machine
- Mode Operation Function Control
- Extra Mold Safety Sensor (Optional) Overload Protection
- Conveyor Control

- Multi Language Support
- Operation Record Feature
- Alarm Record Feature
- USB Memory Connection
- Memory of upto 999 Molds
- Ejector Control
- Euromap 12/67 Robot Interface
- Economic Vacuum Feature (Optional)

MW 1400II













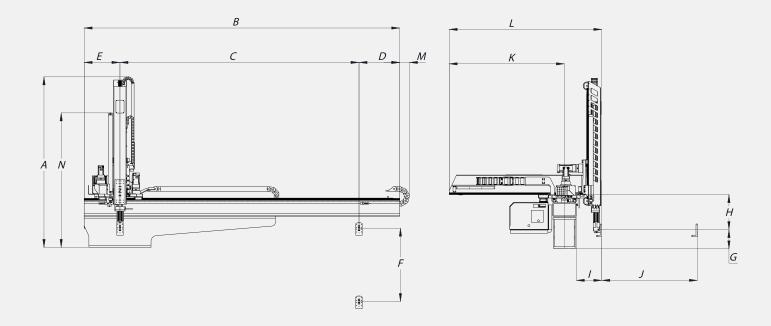




FUNDAMENTAL MECHANICAL SPECIFICATIONS

	Axis	Strokes (r	mm)	Injection Clamping	Driving	Lineer Position	C Axis Postu	re 🗸 90°	Net Weight (kg)
Model	Vertical	Crosswise	Traverse	Force Range (Ton)	Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body
MW1400II	1400 [1600]	1000	2500 [3000]	400 - 650	AC Servo Motor	±0.1	15	65	634 [646] - [665] [674]

(*1) Weight of Robotic Hand is Included.



Α	Height 1851	- [1951]
В	Length 3300 -	[3800]
С	Traverse Axis Stroke 2500 -	[3000]
D	Traverse Axis Stroke Excluded Distance (Product Place Region)	425
Ε	Traverse Axis Stroke Excluded Distance (Product Pick Up Region)	375
F	Vertical Axis Stroke 1400	- [1600]
М	Traverse Axis Cable Carrier Overflow	100
N	Balance Cylinder Height 1407	- [1507]

G	Vertical Wait	200
Н	Gripper Assembly Position under Crosswise Axis	366
ı	Minimum Crosswise Wait	266
J	Maximum Crosswise Stroke	1000
l+J	Maximum Crosswise Reach	1266
L	Width	1600
K	Crosswise Start Distance	1205

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	1.9	4 - 6	13.0 [26.0]

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

([]) Optional Dimensions.

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking
- Product Sorting in Matrix Form
- Soft Sorting / Separation

- Y Axis Free
- Eco Mode (Automatic Energy Saving Cycle Feature)
- Product Extraction from Core in the Mold
- Sprue Separation
- Sample Separation
- Crosswise J (Pass) Motion
- Defective Product Separation (Machine Feature Compatibility Support)
- Message Support on the Control Panel
- IMM Door Open Permission during Pause

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- Extra Mold Safety Sensor (Optional)
- Overload Protection
- Conveyor Control

- Multi Language Support
- Operation Record Feature
- Alarm Record Feature
- USB Memory Connection
- Memory of upto 999 Molds
- Ejector Control
- Euromap 12/67 Robot Interface
- Economic Vacuum Feature (Optional)

MW 1800II













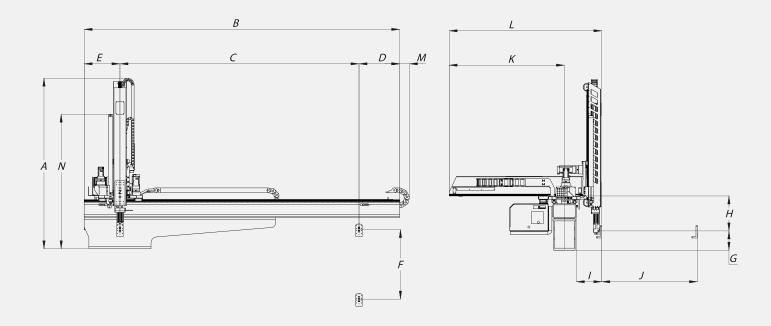




► FUNDAMENTAL MECHANICAL SPECIFICATIONS

Model	Axis Strokes (mm)			Injection Clamping	Driving		Net Weight (kg)		
	Vertical	Crosswise	Traverse	Force Range (Ton)	Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body
MW1800II	1800	1300	2500 [3000]	650 - 1300	AC Servo Motor	±0.1	25	65	656 [690]

(*1) Weight of Robotic Hand is Included.



Α	Height	2060
В	Length 3300 - 	[3800]
С	Traverse Axis Stroke 2500 - [[3000]
D	Traverse Axis Stroke Excluded Distance (Product Place Region)	425
Ε	Traverse Axis Stroke Excluded Distance (Product Pick Up Region)	375
F	Vertical Axis Stroke	1800
M	Traverse Axis Cable Carrier Overflow	100
N	Balance Cylinder Height	1607

G	Vertical Wait	200
Н	Gripper Assembly Position under Crosswise Axis	366
I	Minimum Crosswise Wait	266
J	Maximum Crosswise Stroke	1300
I+J	Maximum Crosswise Reach	1566
L	Width	1900
K	Crosswise Start Distance	1503

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	1.9	4 - 6	13.0 [26.0]

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

([]) Optional Dimensions.

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking
- Product Sorting in Matrix Form
- Soft Sorting / Separation

- Y Axis Free
- Eco Mode (Automatic Energy Saving Cycle Feature)
- Product Extraction from Core in the Mold
- Sprue Separation
- Sample Separation
- Crosswise J (Pass) Motion
- Defective Product Separation (Machine Feature Compatibility Support)
- Message Support on the Control Panel
- IMM Door Open Permission during Pause

- Pause during Operation
- C Axis Rotation Control
- 90° Soft Stop
- Connection Adapter between Robot and Injection Machine
- Mode Operation Function Control
- Extra Mold Safety Sensor (Optional)
- Overload Protection
- Conveyor Control

- Multi Language Support
- Operation Record Feature
- Alarm Record Feature
- USB Memory Connection
- Memory of upto 999 Molds
- Ejector Control
- Euromap 12/67 Robot Interface
- Economic Vacuum Feature (Optional)

MW 2500II













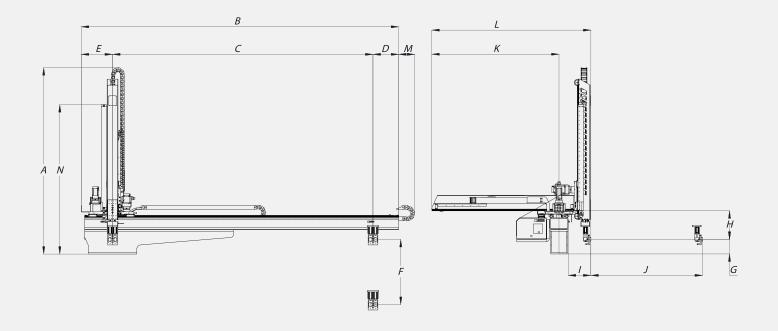




► FUNDAMENTAL MECHANICAL SPECIFICATIONS

	Axis	Strokes (r	nm)	Injection Clamping	Driving	Lineer Position	C Axis Postu	re 🗸 90°	Net Weight (kg)
Model	Vertical	Crosswise	Traverse	Force Range (Ton)	Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body
MW2500II	2500	1500	3500 [4500]	1000 - 2800	AC Servo Motor	±0.1	35	65	795 [846]

^(*1) Weight of Robotic Hand is Included.



Α	Height	2450
В	Length 4265 -	[5265]
С	Traverse Axis Stroke 3500 - 	[4500]
D	Traverse Axis Stroke Excluded Distance (Product Place Region)	345
E	Traverse Axis Stroke Excluded Distance (Product Pick Up Region)	420
F	Vertical Axis Stroke	2500
M	Traverse Axis Cable Carrier Overflow	215
N	Balance Cylinder Height	2007

G	Vertical Wait	195
Н	Gripper Assembly Position under Crosswise Axis	383
I	Minimum Crosswise Wait	303
J	Maximum Crosswise Stroke	1500
l+J	Maximum Crosswise Reach	1803
L	Width	2140
K	Crosswise Start Distance	1708

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	3.3	4 - 6	26.0

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

([]) Optional Dimensions.

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking
- Product Sorting in Matrix Form
- Soft Sorting / Separation

- Y Axis Free
- Eco Mode (Automatic Energy Saving Cycle Feature)
- Product Extraction from Core in the Mold
- Sprue Separation
- Sample Separation
- Crosswise J (Pass) Motion
- Defective Product Separation (Machine Feature Compatibility Support)
- Message Support on the Control Panel
- IMM Door Open Permission during Pause

- Pause during Operation
- C Axis Rotation Control
- 90° Soft Stop
- Connection Adapter between Robot and Injection Machine
- Mode Operation Function Control
- Extra Mold Safety Sensor (Optional)
- Overload Protection
- Conveyor Control

- Multi Language Support
- Operation Record Feature
- Alarm Record Feature
- USB Memory Connection
- Memory of upto 999 Molds
- Ejector Control
- Euromap 12/67 Robot Interface
- Economic Vacuum Feature (Optional)

MWH 1800II













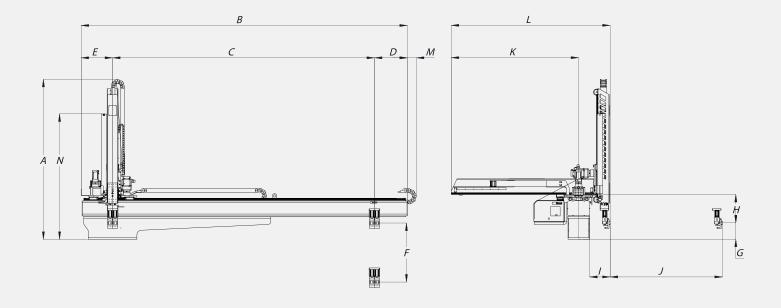




► FUNDAMENTAL MECHANICAL SPECIFICATIONS

	Axis Strokes (mm)		Injection Clamping	Driving	Lineer Position	C Axis Postu	re 🗸 90°	Net Weight (kg)	
Model	Vertical	Crosswise	Traverse	Force Range (Ton)	Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body
MWH1800II	1800 [2500]	1500	3500	1000 - 2800	AC Servo Motor	±0.1	45 (*1)	100	1254 [1265]

(*1) Weight of Robotic Hand is Included.



Α	Height 214	0 - [2490]
В	Length	4360
C	Traverse Axis Stroke	3500
D	Traverse Axis Stroke Excluded Distance (Product Place Region)	440
E	Traverse Axis Stroke Excluded Distance (Product Pick Up Region)	420
F	Vertical Axis Stroke 180	0 - [2500]
M	Traverse Axis Cable Carrier Overflow	125
N	Balance Cylinder Height 167	76 - [2026]

Vertical Wait	220
Gripper Assembly Position under Cross	swise Axis 380
Minimum Crosswise Wait	272
Maximum Crosswise Stroke	1500
Maximum Crosswise Reach	1772
Width	2125
Crosswise Start Distance	1703
	Gripper Assembly Position under Cross Minimum Crosswise Wait Maximum Crosswise Stroke Maximum Crosswise Reach Width

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	3.3	4 - 6	26.0

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

([]) Optional Dimensions.

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking
- Product Sorting in Matrix Form
- Soft Sorting / Separation

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- Memory of upto 999 Molds
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- Economic Vacuum Feature (Optional)

MWH 2500II













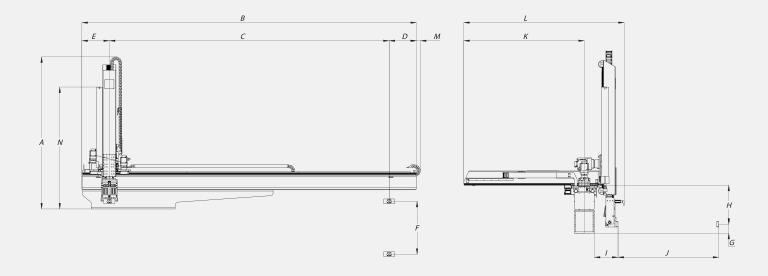




FUNDAMENTAL MECHANICAL SPECIFICATIONS

	Axis Strokes (mm)			Injection Clamping	Driving Method	Lineer Position C Axis Posture > 90°	C Axis Posture 🔍 90 º		Net Weight (kg)
Model	Vertical	Il Crosswise Traverse (Ton)	Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body		
MWH2500II	2500 [3000]	1500	5000 [4500] [3500]	1300 - 2800	AC Servo Motor	±0.1	60	550	2015 - [2215] [1895] - [2095] [1715] - [1915]

(*1) Weight of Robotic Hand is Included.



Α	Height	2710 -	[2960]
В	Length	5980	[5480] [4480]
С	Traverse Axis Stroke	5000	[3500] [4500]
D	Traverse Axis Stroke Excluded Dista (Product Place Region)	ence	490
Ε	Traverse Axis Stroke Excluded Dista (Product Pick Up Region)	ence	490
F	Vertical Axis Stroke	2500 -	[3000]
M	Traverse Axis Cable Carrier Overflo	N	75
N	Balance Cylinder Height	2180 -	[2430]

G	Vertical Wait	115
Н	Gripper Assembly Position under Crosswis	se Axis 600
ı	Minimum Crosswise Wait	355
J	Maximum Crosswise Stroke	1500
l+J	Maximum Crosswise Reach	1855
L	Width	2390
K	Crosswise Start Distance	1795

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	4.1	4 - 6	195.0

GENERAL FEATURES

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking
- Product Sorting in Matrix Form
- Soft Sorting / Separation

Y Axis Free

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

- Eco Mode (Automatic Energy Saving Cycle Feature)
- Product Extraction from Core in the Mold
- Sprue Separation
- Sample Separation
- Crosswise J (Pass) Motion
- Defective Product Separation (Machine Feature Compatibility Support)
- Message Support on the Control Panel
- IMM Door Open Permission during Pause

- Pause during Operation
- C Axis Rotation Control
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- Connection Adapter between Robot and Injection Machine
 Mode Operation Function Control

- Extra Mold Safety Sensor (Optional)
- Overload Protection
- Conveyor Control

- Multi Language Support
- Operation Record Feature
- · Alarm Record Feature
- USB Memory Connection
- Memory of upto 999 Molds
- Ejector Control
- Euromap 12/67 Robot Interface
- Economic Vacuum Feature (Optional)

MWH 3000II













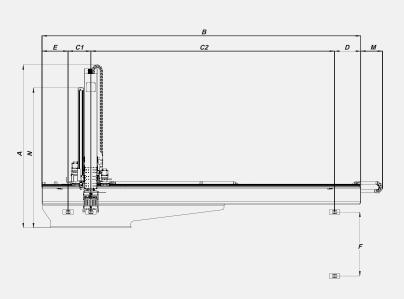


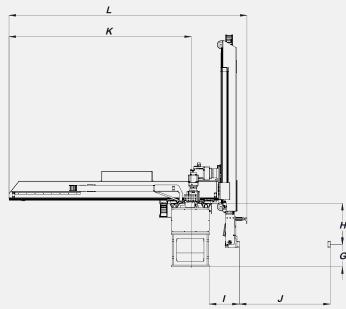


► FUNDAMENTAL MECHANICAL SPECIFICATIONS

	Axis S	trokes (m	m)	Injection Clamping	Driving	Lineer Position	C Axis Posture 📏 90 º		Net Weight (kg)
Model	Vertical	Crosswise	Force Range (Ton)		Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body
MWH3000II	3000	2000	5000	1300 - 2800	AC Servo Motor	±0.1	60	550	3200

^(*1) Weight of Robotic Hand is Included.





Α	Height	3059
В	Length	5980
С	C 1+C2 Traverse Axis Stroke	5000
D	Traverse Axis Stroke Excluded Distance (Product Place Region)	490
Ε	Traverse Axis Stroke Excluded Distance (Product Pick Up Region)	490
F	Vertical Axis Stroke	3000
M	Traverse Axis Cable Carrier Overflow	376
N	Balance Cylinder Height	2629

G	Vertical Wait	296
Н	Gripper Assembly Position under Crosswise	Axis 541
ı	Minimum Crosswise Wait	396
J	Maximum Crosswise Stroke	2000
l+J	Maximum Crosswise Reach	2396
L	Width	3138
K	Crosswise Start Distance	2405

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	4.1	4 - 6	195.0

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

([]) Optional Dimensions.

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking
- Product Sorting in Matrix Form
- Soft Sorting / Separation

- Y Axis Free
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- Memory of upto 999 Molds
- Ejector Control
- Euromap 12/67 Robot Interface
- Economic Vacuum Feature (Optional)

SCH 120011













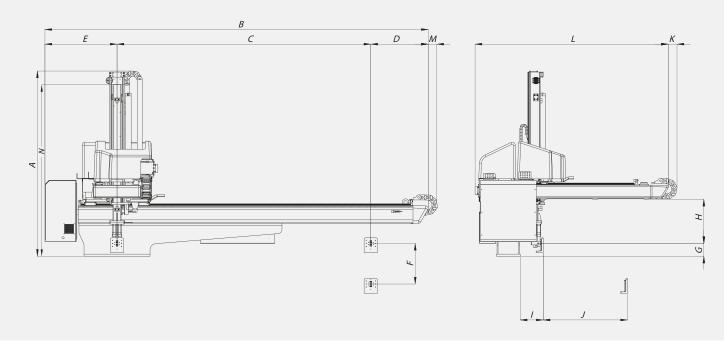




FUNDAMENTAL MECHANICAL SPECIFICATIONS

	Axis:	Strokes (r	nm)	Injection Clamping	Driving	Lineer Position	C Axis Postu	C Axis Posture 90°	
Model	Vertical	Crosswise	Traverse	Force Range (Ton)	Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body
SCH 1200II	1200	680	1800	250 - 400	AC Servo Motor	±0.1	10	65	670

^(*1) Weight of Robotic Hand is Included.



Α	Height	1675
В	Length	3025
С	Traverse Axis Stroke	1800
D	Traverse Axis Stroke Excluded Distance (Product Place Region)	520
E	Traverse Axis Stroke Excluded Distance (Product Pick Up Region)	710
F	Vertical Axis Stroke	1200
M	Traverse Axis Cable Carrier Overflow	230
N	Balance Cylinder Height	1410

G	Vertical Wait	118
Н	Gripper Assembly Position under Crossw	ise Axis 440
ı	Minimum Crosswise Wait	256
J	Maximum Crosswise Stroke	680
l+J	Maximum Crosswise Reach	936
L	Width	1685
K	Crosswise Start Distance	160

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	4.3	4 - 6	3.5

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking
- Product Sorting in Matrix Form
- Soft Sorting / Separation

- Y Axis Free
- Eco Mode (Automatic Energy Saving Cycle Feature)
- Product Extraction from Core in the Mold
- Sprue Separation
- Sample Separation
- Crosswise J (Pass) Motion
- Defective Product Separation (Machine Feature Compatibility Support)
- Message Support on the Control Panel
- IMM Door Open Permission during Pause

- Pause during Operation
- C Axis Rotation Control
- 90° Soft Stop
- Connection Adapter between Robot and Injection Machine
 Mode Operation Function Control
- Extra Mold Safety Sensor (Optional)
- Overload Protection
- Conveyor Control

- Multi Language Support
- Operation Record Feature
- · Alarm Record Feature
- USB Memory Connection
- Memory of upto 999 Molds
- Ejector Control
- Euromap 12/67 Robot Interface
- Economic Vacuum Feature (Optional)

SCH 1600II













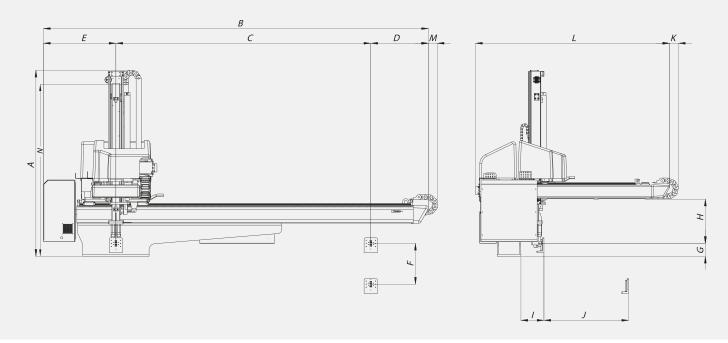




FUNDAMENTAL MECHANICAL SPECIFICATIONS

	Axis:	Strokes (r	nm)	Injection Clamping	Driving	Lineer Position	C Axis Postu	C Axis Posture 90°	
Model	Vertical	Crosswise	Traverse	Force Range (Ton)	Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body
SCH 1600II	1600	830	2.550	400 - 850	AC Servo Motor	±0.1	35	65	700

^(*1) Weight of Robotic Hand is Included.



Height	1825
Length	3725
Traverse Axis Stroke	2500
Traverse Axis Stroke Excluded Distance (Product Place Region)	520
Traverse Axis Stroke Excluded Distance (Product Pick Up Region)	710
Vertical Axis Stroke	1600
Traverse Axis Cable Carrier Overflow	230
Balance Cylinder Height	1610
	Length Traverse Axis Stroke Traverse Axis Stroke Excluded Distance (Product Place Region) Traverse Axis Stroke Excluded Distance (Product Pick Up Region) Vertical Axis Stroke Traverse Axis Cable Carrier Overflow

G	Vertical Wait	118
Н	Gripper Assembly Position under Crossw	ise Axis 440
I	Minimum Crosswise Wait	256
J	Maximum Crosswise Stroke	830
l+J	Maximum Crosswise Reach	1086
L	Width	1835
K	Crosswise Start Distance	160

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	4,3	4 - 6	3.5

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking
- Product Sorting in Matrix Form
- Soft Sorting / Separation

- Y Axis Free
- Eco Mode (Automatic Energy Saving Cycle Feature)
- Product Extraction from Core in the Mold
- Sprue Separation
- Sample Separation
- Crosswise J (Pass) Motion
- Defective Product Separation (Machine Feature Compatibility Support)
- Message Support on the Control Panel
- IMM Door Open Permission during Pause

- Pause during Operation
- C Axis Rotation Control
- 90° Soft Stop
- Connection Adapter between Robot and Injection Machine
 Mode Operation Function Control
- Extra Mold Safety Sensor (Optional)
- Overload Protection
- Conveyor Control

- Multi Language Support
- Operation Record Feature
- · Alarm Record Feature
- USB Memory Connection
- Memory of upto 999 Molds
- Ejector Control
- Euromap 12/67 Robot Interface
- Economic Vacuum Feature (Optional)

eMW 800II

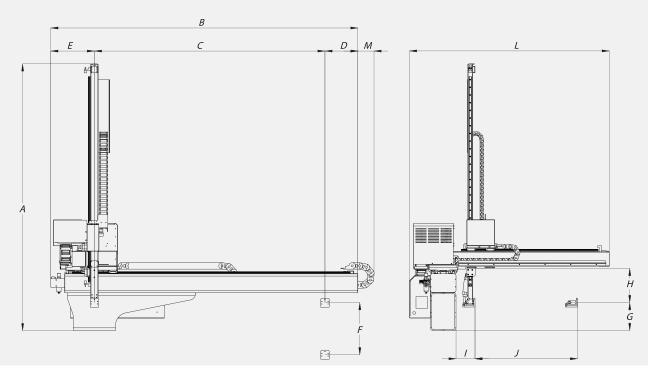




► FUNDAMENTAL MECHANICAL SPECIFICATIONS

	Axis	Strokes (r	mm)	Injection Clamping	Driving	Lineer Position	C Axis Postu	C Axis Posture 90°	
Model	Vertical	Crosswise	Traverse	Force Range (Ton)	Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body
eMW800	800	450	1200	50 - 150	AC Servo Motor	±0.1	3	25	260

(*1) Weight of Robotic Hand is Included.



Α	Height	1685
В	Length	1800
С	Traverse Axis Stroke	1200
D	Traverse Axis Stroke Excluded Distance (Product Place Region)	260
Ε	Traverse Axis Stroke Excluded Distance (Product Pick Up Region)	340
F	Vertical Axis Stroke	800
M	Traverse Axis Cable Carrier Overflow	130

G	Vertical Wait	215
Н	Gripper Assembly Position under Crosswise Ax	is 265
ı	Minimum Crosswise Wait	150
J	Maximum Crosswise Stroke	450
l+J	Maximum Crosswise Reach	600
L	Width	1210

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	1.3	4 - 6	2.5

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking
- Product Sorting in Matrix Form
- Soft Sorting / Separation

- Y Axis Free
- Eco Mode (Automatic Energy Saving Cycle Feature)
- Product Extraction from Core in the Mold
- Sprue Separation
- Sample Separation
- Crosswise J (Pass) Motion
- Defective Product Separation (Machine Feature Compatibility Support)
- Message Support on the Control Panel
- IMM Door Open Permission during Pause

- Pause during Operation
- C Axis Rotation Control
- 90° Soft Stop
- Connection Adapter between Robot and Injection Machine
- Mode Operation Function Control
- Extra Mold Safety Sensor (Optional)
- Overload Protection
- Conveyor Control

- Multi Language Support
- Operation Record Feature
- Alarm Record Feature
- USB Memory Connection
- Memory of upto 50 Molds
- Ejector Control
- Euromap 12/67 Robot Interface
- Economic Vacuum Feature (Optional)

eMW 1000II





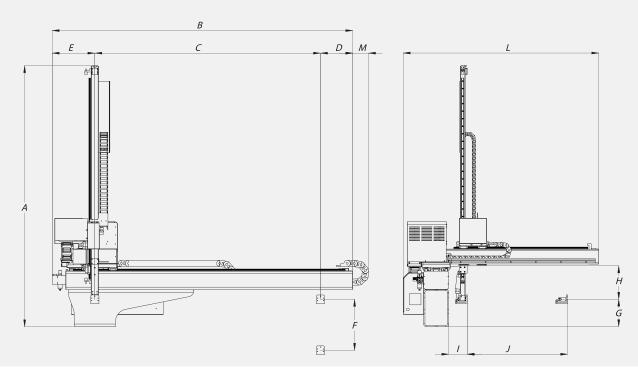




FUNDAMENTAL MECHANICAL SPECIFICATIONS

Model	Axis Strokes (mm)		Injection Driving	Lineer Position	C Axis Post	Net Weight (kg)			
	Vertical	Crosswise	Traverse	Force Range (Ton)	Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body
eMW1000	1000	660	1500	100 - 380	AC Servo Motor	±0.1	(*1)	25	280

^(*1) Weight of Robotic Hand is Included.



Α	Height	1885
В	Length	2100
С	Traverse Axis Stroke	1500
D	Traverse Axis Stroke Excluded Distance (Product Place Region)	260
Ε	Traverse Axis Stroke Excluded Distance (Product Pick Up Region)	340
F	Vertical Axis Stroke	1000
M	Traverse Axis Cable Carrier Overflow	130

G	Vertical Wait	215
Н	Gripper Assembly Position under Crosswise	Axis 265
I	Minimum Crosswise Wait	150
J	Maximum Crosswise Stroke	660
l+J	Maximum Crosswise Reach	810
L	Width	1420

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	1.3	4 - 6	3.5

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking Product Sorting in Matrix Form
- Soft Sorting / Separation

- Y Axis Free
- Eco Mode (Automatic Energy Saving Cycle Feature)
- Product Extraction from Core in the Mold
- Sprue Separation
- Sample Separation
- Crosswise J (Pass) Motion
- Defective Product Separation (Machine Feature Compatibility Support)
- Message Support on the Control Panel
- IMM Door Open Permission during Pause

- Pause during Operation
- C Axis Rotation Control
- 90° Soft Stop
- Connection Adapter between Robot and Injection Machine
- Mode Operation Function Control
- Extra Mold Safety Sensor (Optional)
- Overload Protection
- Conveyor Control

- Multi Language Support
- Operation Record Feature
- Alarm Record Feature
- USB Memory Connection
- Memory of upto 50 Molds
- Ejector Control
- Euromap 12/67 Robot Interface
- Economic Vacuum Feature (Optional)

eMW 1200II

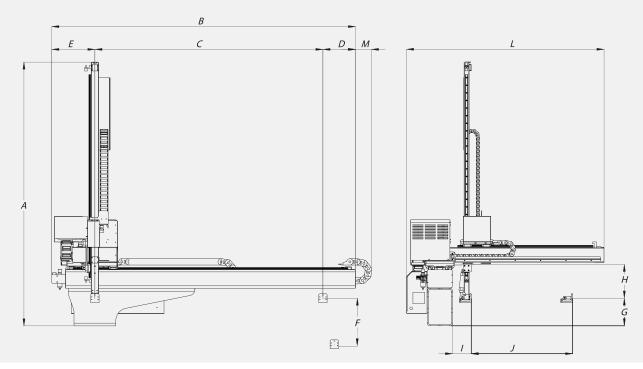




► FUNDAMENTAL MECHANICAL SPECIFICATIONS

	AXIS Strokes (mm)		Clamping	Lineer Position	C Axis Postu	Net Weight (kg)			
Model	Vertical	Crosswise	Traverse	Force Range (Ton)	Method	Repeatibility (mm)	Maximum Payload (kg)	C Axis Posture Torque (Nm)	Main Body
eMW1200	1200	800	1800	300 - 660	AC Servo Motor	±0.1	12	25	310

(*1) Weight of Robotic Hand is Included.



Α	Height	2085
В	Length	2400
С	Traverse Axis Stroke	1800
D	Traverse Axis Stroke Excluded Distance (Product Place Region)	260
Ε	Traverse Axis Stroke Excluded Distance (Product Pick Up Region)	340
F	Vertical Axis Stroke	1200
M	Traverse Axis Cable Carrier Overflow	130

G	Vertical Wait	215
Н	Gripper Assembly Position under Crosswise A	Axis 265
I	Minimum Crosswise Wait	150
J	Maximum Crosswise Stroke	800
l+J	Maximum Crosswise Reach	950
L	Width	1560

Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Three-phase AC 380V ± %10 (50Hz/60 Hz)	1.6	4 - 6	4.5

(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

- Vacuum Line
- Blow Line
- Sprue Gripper Line
- Product Pickup from Fixed and Moving Platens
- Troduct rickup ironi rixcu dila Moving riaten
- \cdot Selection of Operator / Non-operator Working Direction
- Vacuum Level Adjustment on the Control Panel
- Product Sorting and Stacking
- Product Sorting in Matrix Form
- Soft Sorting / Separation

- Y Axis Free
- Eco Mode (Automatic Energy Saving Cycle Feature)
- Product Extraction from Core in the Mold
- Sprue Separation
- Sample Separation
- Crosswise J (Pass) Motion
- Defective Product Separation (Machine Feature Compatibility Support)
- Message Support on the Control Panel
- IMM Door Open Permission during Pause

- Pause during Operation
- C Axis Rotation Control
- 90° Soft Stop
- Connection Adapter between Robot and Injection Machine
- Mode Operation Function Control
- Extra Mold Safety Sensor (Optional)
- Overload Protection
- Conveyor Control

- Multi Language Support
- Operation Record Feature
- Alarm Record Feature
- USB Memory Connection
- Memory of upto 50 Molds
- Ejector Control
- Euromap 12/67 Robot Interface
- Economic Vacuum Feature (Optional)

MPR 650









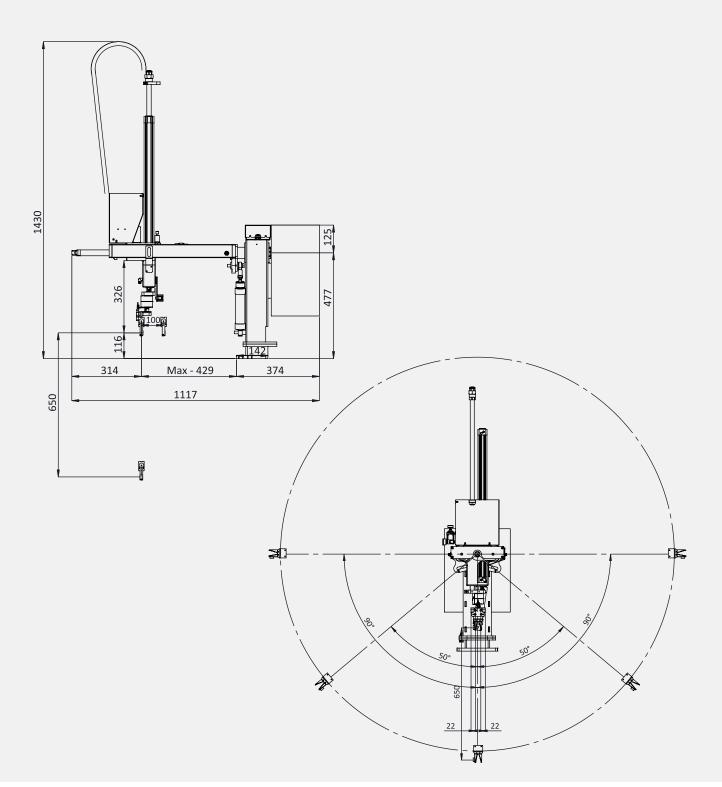




FUNDAMENTAL MECHANICAL SPECIFICATIONS

	Axis	Axis Strokes (mm)		Driving		Maximum	Main Bodu	
Model	Vertical	Crosswise	Max. Access	. .	Axis Posture	Payload (kg)	Main Body (kg)	
MPR 650	650	100	450	Pneumatic	50°-90°	(*1)	50	

^(*1) Weight of Robotic Hand is Included.



Power Supply	Maximum Power (kW)	Air Pressure (Bar)	Air Consumption (NI/Cycle)
Mono-phase AC 220V ± %10 (50Hz/60 Hz)	0,3 A	4 - 6	9

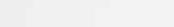
(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.

- Free Program
- Multi Language Support
- Product Pickup from Fixed and Moving Platens
- · Selection of Operator / Non-operator Working Direction
- Euromap 12/67 Robot Interface
- Crosswise J (Pass) Motion
- Sprue Control
- Ejector Control
- IMM Door Open Permission during Pause
- Pause during Operation
- Extra Mold Safety Sensor (Optional)
- USB Memory Connection
- Connection Adapter between Robot and Injection Machine
- Conveyor Control
- Vacuum General (Optional)

SIDE - ENTRY ROBOTS









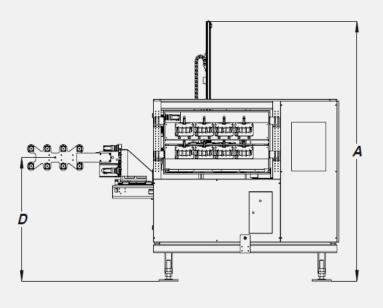


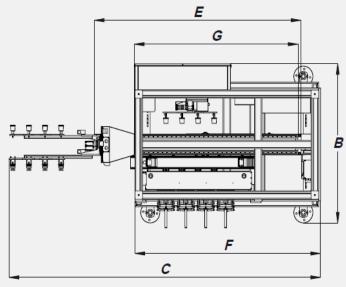
Data varies depending on the project.

Power Supply		Maximum Power Consumption	Air Pressure	Air Consumption	Net Weight (kg)	
Power Supply	(kVA)	(kW)	(Bar)	(NI/Cycle)	Main Body	Hand Panel
Three-phase AC 380V ±	8.9	5.34	6~8	2.6	1630 1.1	11
%10 (50/60Hz)	8.9	(*1)	(*2)	2.0		1.1

^(*1) It is calcutated value approximately % 60 efficiency rate based on electricity consumption.

^(*2) Need for Pressurized Air Purified (Dried) from Oil and Humidity Exists.





Dimensions and designs vary depending on the project.

B Width	1800
C Length	3870 (*4)

D	In mold axis height (Adjustible)	1490-1590
Е	Traverse Axis	2500
F	Chassis Length	2425
G	Stroke	1900

(*3) Maximum value for height.

(*4) Maximum value for length.

- Vacuum Line
- Blow Line
- · Vacuum Level Adjustment on the Control Panel | · Extra Mold Safety Sensor
- Product Sorting and Stacking
- Y Axis Free
- Product Pickup from Fixed and Moving Platens | Defective Product Separation (Machine Feature Compatibility Support)

- Conveyor Control
- Multi Language Support
- Operation Record Feature
- Alarm Record Feature
- USB Memory Connection
- Memory of upto 50 Molds
- Ejector Control
- Euromap 12/67 Robot Interface



AUTOMATION SOLUTIONS







SECTORS



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